Decision Making Under Uncertainty: Lecture 2—Sample Average Approximation

Lecture 2 Ryan Cory-Wright Spring 2024 • Reminder: Please name paper you are presenting for critical paper review and week you are presenting in (by email to me) by Friday.

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- My next office hours are today 3-4pm.

$$\begin{array}{ll} \min_{x_1, x_2} & x_1 + x_2 \\ \text{s.t.} & \omega_1 x_1 + x_2 \geq 7 \\ & \omega_2 x_1 + x_2 \geq 4 \\ & x_1, x_2 \geq 0 \end{array}$$

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Conclusion: Terminology matters, should define everything carefully!

Motivation: Ordinary Least Squares Regression

Sample Average Approximation: Theory Newsvendor: A Special Case That We Can Solve The General Problem

Sample Average Approximation: Algorithmics

Can we do Better? Ridge Regression and Sample-Average Approximation

Activities for if we Finish Early

Suggested Readings

Motivation: Ordinary Least Squares Regression

Linear regression: *n* i.i.d. observations of *p*-dimensional input vector **x** and output *y*, $\{(\mathbf{x}_i, y_i)\}_{i=1}^n$. We believe input-output follows model $y = \mathbf{x}^\top \beta_{\text{true}} + \epsilon$, where β_{true} fixed vector, ϵ i.i.d. zero-mean noise.

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How to estimate β ? Typical answer: minimize OLS error

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After some calculus

$$\hat{\boldsymbol{\beta}} = (\boldsymbol{X}^{\top}\boldsymbol{X})^{\dagger}\boldsymbol{X}^{\top}\boldsymbol{y},$$

where \mathbf{A}^{\dagger} denotes pseudoinverse of \mathbf{A} .

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$$\hat{eta} = (m{X}^{ op}m{X})^{\dagger}m{X}^{ op}m{y} \underbrace{=}_{ ext{substitute } m{y} = m{X}eta + \epsilon} eta_{ ext{true}} + (m{X}^{ op}m{X})^{\dagger}m{X}^{ op}m{\epsilon}$$

If **X** a matrix with singular value decomposition $\mathbf{X} = \mathbf{U} \Sigma \mathbf{V}^{\top}$ Then $\mathbf{X} = \mathbf{U} \Sigma^{\dagger} \mathbf{V}^{\top}$ where Σ^{\dagger} is a diagonal matrix where we invert all non-zero diagonal entries, keep zeroes as zeroes.

For a symmetric matrix like $\mathbf{X}^{\top}\mathbf{X}$, can define

$$(\boldsymbol{X}^{ op}\boldsymbol{X})^{\dagger} := \lim_{\lambda o 0} (\boldsymbol{X}^{ op}\boldsymbol{X} + \lambda \mathbb{I})^{-1}.$$

See the book "Matrix Analysis" by Horn and Johnson.

Almost Sure Definition

Let $(\Omega, \mathcal{F}, \mathbb{P})$ be a probability space and let $\{X_i\}_{i \in \mathbb{N}}, X$ be random variables. Suppose that $A \in \mathcal{F}$ is a measurable set such that $\mathbb{P}(A) = 1$ and for all $\omega \in A$ we have

$$\boldsymbol{X}_{i}(\omega)
ightarrow \boldsymbol{X}(\omega).$$

Then, we say that $X_i \stackrel{a.s.}{\rightarrow} X$.

Continuous Mapping Theorem

Let X_i, X be random variables. Suppose that $X_i \xrightarrow{a.s.} X$ and f is continuous almost everywhere. Then

 $f(\boldsymbol{X}_i) \stackrel{a.s.}{\rightarrow} f(\boldsymbol{X})$

Consider our rearranged equation:

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- SLLN $\frac{1}{n} X X^{\top} \stackrel{a.s.}{\rightarrow} \mathbb{E}[x_i x_i^{\top}]$
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Figure 1: Thanos Explains Empirical Risk Minimization

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find estimator with least variance, (2) treating each obs. as equally likely, replacing expectation with sample-average approximation

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- Plan for lecture: Show holds more generally, how to solve SAA

Let's break for five minutes here
Sample Average Approximation: Theory

Let's warm up with a special case

• A newsvendor (newspaper salesperson) needs to decide how many newspapers x to buy to maximize their profit

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- She doesn't know how many newspapers there are demand for, D_{ω} in scenario ω . But she does know the probability distribution of D_{ω}
- Each newspaper costs c, can be sold for q if there is demand
- Unsold newspapers get thrown in the recycling bin
- How to optimally set x?

Hot off the Press: The Newsvendor Problem

$$\max_{x\geq 0}\mathbb{E}_{\omega}[\min(D_{\omega},x)q-cx]$$

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That is, a $\frac{(q-c)}{q}$ th quantile of D_{ω} Insight: setting x equal to $\mathbb{E}[D_{\omega}]$ could be bad, especially if $q \gg c$

The General Problem

Consider stochastic optimization problem:

$$\min_{\boldsymbol{x}\in\mathbb{R}^n} \quad \boldsymbol{c}^{\top}\boldsymbol{x} + \mathbb{E}_{\omega}[h(\boldsymbol{x},\boldsymbol{\omega})]$$

s.t.
$$Ax \leq b$$

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- A linear optimization problem with random parameters

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- Structure of Optimal Solutions: In general, ${\it y}$ a function of ω

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- As n→∞, for i.i.d. ωⁱ, x̂ almost surely converges to a minimizer of our two-stage problem under true joint distribution of ω
- Who can tell me why we use "arg min" and "a minimizer" here?

• Define a sample-average function, redefine expected value

$$egin{aligned} \hat{g}_N(m{x}) &:= \min_{m{y}(\omega^i)} m{c}^ op m{x} + rac{1}{N} \sum_{i=1}^n h(m{x}, \omega^i), \ g(m{x}) &:= \min_{m{y}(\omega)} \mathbb{E}_\omega[m{c}^ op m{x} + rac{1}{N} \sum_{i=1}^n h(m{x}, \omega)] \end{aligned}$$

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Duality!

$$h(\boldsymbol{x}, \boldsymbol{\omega}) = \max_{\boldsymbol{\mu}(\omega)} \quad (\boldsymbol{d}(\boldsymbol{\omega}) - \boldsymbol{D}(\omega)\boldsymbol{x})^{\top}\boldsymbol{\mu}(\omega) \text{ s.t. } \boldsymbol{F}(\omega)^{\top}\boldsymbol{\mu}(\omega) = \boldsymbol{q}(\boldsymbol{\omega}), \boldsymbol{\mu}(\omega) \leq \boldsymbol{0}$$

h is the optimal value of a minimization problem. Why is it convex?



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 $h(\mathbf{x}, \boldsymbol{\omega})$ is the pointwise maximum of functions linear in \mathbf{x} , hence convex
Aside

h is the optimal value of a minimization problem. Why is it convex?



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 $h(x, \omega)$ is the pointwise maximum of functions linear in x, hence convex Pointwise maximum also reveals h is continuous on its domain • Define a sample-average function, redefine expected value

$$egin{aligned} \hat{g}_{\mathcal{N}}(oldsymbol{x}) :=& oldsymbol{c}^{ op}oldsymbol{x} + rac{1}{\mathcal{N}}\sum_{i=1}^{\mathcal{N}}h(oldsymbol{x},\omega^i), \ & g(oldsymbol{x}) :=& oldsymbol{c}^{ op}oldsymbol{x} + \mathbb{E}_{\omega}[h(oldsymbol{x},\omega)] \end{aligned}$$

• By SLLN, continuity of $g_N, g: g_N(\mathbf{x}) \stackrel{a.s.}{\rightarrow} g(\mathbf{x}) \ \forall \mathbf{x} : \mathbf{A}\mathbf{x} \leq \mathbf{b}$

¹See Corollary 3 of "Monte Carlo Sampling Methods" by Shapiro (2003) for details.

• Define a sample-average function, redefine expected value

$$\hat{g}_N(oldsymbol{x}) := oldsymbol{c}^ op oldsymbol{x} + rac{1}{N} \sum_{i=1}^N h(oldsymbol{x}, oldsymbol{\omega}^i), \ g(oldsymbol{x}) := oldsymbol{c}^ op oldsymbol{x} + \mathbb{E}_\omega[h(oldsymbol{x}, oldsymbol{\omega})]$$

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- Therefore, (under mild conditions¹), $\inf_{x} g_{N}(x) \stackrel{a.s.}{\rightarrow} \inf_{x} g(x)$

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When Things go Wrong, as They Sometimes Will

Let's look at our sample-average approximation again:

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- \hat{x}_N might be far from x^* , especially if N small relative to dim of x
 - A motivation for distributionally robust optimization—see later

Let's break for five minutes. Then talk about how to solve these problems

Sample Average Approximation: Algorithmics

We can view the sample-average approximation as one big linear optimization problem and throw it to Mosek or Gurobi

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• Make a copy of \mathbf{y}^i for each scenario ω^i and solve

$$\hat{x} \in \arg\min_{x \in \mathbb{R}^n} \quad c^{\top}x + \frac{1}{n}\sum_{i=1}^n h(x, \omega^i)$$

s.t. $Ax < b$

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- Example: electricity market with random demand at 20 nodes that can independently be "low" or "high" That's $2^{20} = 1048576$ copies of y, which is intractable for a real market
- Still, you can sometimes do well by subsampling the scenarios (Shapiro and Homem-de-Mello, 1998)

What optimizers usually do: use a decomposition scheme called Benders decomposition (sometimes called the "L-shaped" method)

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Consider

$$\min_{\boldsymbol{x} \in \mathbb{R}^n} \quad \boldsymbol{c}^\top \boldsymbol{x} + \frac{1}{n} \sum_{i=1}^n h(\boldsymbol{x}, \boldsymbol{\omega}^i)$$
s.t. $\boldsymbol{A} \boldsymbol{x} \leq \boldsymbol{b}$

Let $\theta \geq \frac{1}{n} \sum_{i=1}^{n} h(\mathbf{x}, \omega^{i})$ be an epigraph variable

$$\min_{\mathbf{x} \in \mathbb{R}^n, \theta} \quad \boldsymbol{c}^\top \boldsymbol{x} + \theta$$

s.t. $\boldsymbol{A} \boldsymbol{x} < \boldsymbol{b}$.

$$\min_{\boldsymbol{x}\in\mathbb{R}^n,\theta} \quad \boldsymbol{c}^{\top}\boldsymbol{x}+\theta$$

s.t. $\boldsymbol{A}\boldsymbol{x}\leq\boldsymbol{b}.$

(Sketch) We iteratively

• Solve this "master" problem to find an optimal **x**

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- Solve this "master" problem to find an optimal x
- Evaluate $1/n\sum_{i=1}^n h(\mathbf{x}, \boldsymbol{\omega}^i)$ and add inequalities which model
 - $\theta \geq \frac{1}{n} \sum_{i=1}^{n} h(\mathbf{x}, \boldsymbol{\omega}^{i})$
 - For x to be feasible, there is a feasible $y(\omega^i)$ in each scenario ω^i

until we converge.

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until we converge. We never model $y(\omega^i)$, so we replaced one intractable problem with a sequence of (possibly many) tractable ones

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Remark: About to go through how this works in gory detail. However, I find the best way to understand this method is to code it for yourself.

Suppose we solve

$$\min_{\boldsymbol{x} \in \mathbb{R}^n, \theta} \quad \boldsymbol{c}^\top \boldsymbol{x} + \theta$$

s.t. $\boldsymbol{A} \boldsymbol{x} \leq \boldsymbol{b}.$

and obtain some solution x. Two cases:

There is some scenario ωⁱ for which no y(ω) can make the scenario feasible → we need to tell the master problem that this x is infeasible, via a *feasibility cut*

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- There is some scenario ωⁱ for which no y(ω) can make the scenario feasible → we need to tell the master problem that this x is infeasible, via a *feasibility cut*
- Every scenario ω^i is feasible \rightarrow we need to tell the master problem how much x costs via an *optimality cut*

Benders Decomposition: Feasibility Cut

Suppose we solve

$$\min_{\boldsymbol{\in}\mathbb{R}^n,\boldsymbol{\theta}} \quad \boldsymbol{c}^{\top}\boldsymbol{x} + \boldsymbol{\theta}$$

s.t. $\boldsymbol{A}\boldsymbol{x} \leq \boldsymbol{b}$.

x

and obtain some solution x such that in scenario i no $y(\omega)$ can make the scenario feasible.

Benders Decomposition: Feasibility Cut

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and obtain some solution x such that in scenario i no $y(\omega)$ can make the scenario feasible. Then, the dual problem in this scenario is unbounded (why?), so there is some $\mu(\omega^i)$ such that

$$(\boldsymbol{d}(\boldsymbol{\omega}) - \boldsymbol{D}(\boldsymbol{\omega})\boldsymbol{x})^{\top}\boldsymbol{\mu}(\boldsymbol{\omega}) > 0, \ \boldsymbol{F}(\boldsymbol{\omega})^{\top}\boldsymbol{\mu}(\boldsymbol{\omega}) = \boldsymbol{q}(\boldsymbol{\omega}), \boldsymbol{\mu}(\boldsymbol{\omega}) \leq \boldsymbol{0}.$$

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Therefore, we fix $\mu(\omega^i)$ and impose the feasibility cut

$$(\boldsymbol{d}(\boldsymbol{\omega}^i) - \boldsymbol{D}(\boldsymbol{\omega}^i)\boldsymbol{x})^\top \boldsymbol{\mu}(\boldsymbol{\omega}^i) \leq 0,$$

in the master problem, where everything but \boldsymbol{x} is data

$$egin{aligned} \min_{oldsymbol{x}\in\mathbb{R}^n, heta} &oldsymbol{c}^{ op}oldsymbol{x}+ heta\ & ext{s.t.} &oldsymbol{A}oldsymbol{x}\leqoldsymbol{b},\ &oldsymbol{(d}(\omega^i)-oldsymbol{D}(\omega^i)oldsymbol{x})^{ op}oldsymbol{\mu}(\omega^i)\leq 0. \end{aligned}$$

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Need cut involving θ , which tells master problem what \boldsymbol{x} costs

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By weak duality, for any $ar{x}$

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Therefore, we add cut

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Sample Average Approximation: Code You will write this yourself in the first assignment :-) Can we do Better? Ridge Regression and Sample-Average Approximation

Can we do Better Than the Sample-Average Approximation?

Returning to Linear Regression

Statisticians don't solve problems like

$$\min_{\boldsymbol{\beta}\in\mathbb{R}^p} \quad \frac{1}{n} \|\boldsymbol{X}\boldsymbol{\beta}-\boldsymbol{y}\|_2^2$$

to pick β , despite SAA's properties. Why not?

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$$\min_{\boldsymbol{\beta}\in\mathbb{R}^p} \quad \frac{1}{n} \|\boldsymbol{X}\boldsymbol{\beta}-\boldsymbol{y}\|_2^2 + R(\boldsymbol{\beta}),$$

where $R(\cdot)$ is a regularization term, e.g., $\frac{1}{2\gamma} \|\beta\|_2^2 + \lambda \|\beta\|_1$ for appropriately chosen λ, γ (elastic net method, Zou and Hastie 2005).

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where $R(\cdot)$ is a regularization term, e.g., $\frac{1}{2\gamma} ||\beta||_2^2 + \lambda ||\beta||_1$ for appropriately chosen λ, γ (elastic net method, Zou and Hastie 2005). This usually performs better out-of-sample.

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- Google "Robust SAA" by Bertsimas et al. (Math. Prog. 2017)

Extension: Accelerating Benders Decomposition for Facility Location

See slides by Fischetti (2017)

Activities for if we Finish Early

Either Prove or Provide a Counterexample for the Following Statements

- The intersection of convex sets is convex.
- The union of convex sets is convex.
- All polyhedral sets are convex.

- Value of Stochastic Solution.
- Value of Perfect Information.

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- 4. Open office hours.

Suggested Readings

Suggested Readings to Accompany Today's Lecture

A friendly reminder:

"To get as much out of this class as possible, we suggest that you spend at least as much time on reading the papers and textbooks referenced in the lectures/reviewing the lectures as you spend in class." — The syllabus A friendly reminder:

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Recommended reading:

• Shapiro, Dentcheva, Ruszczynski *Lectures on Stochastic Programming: Modeling and Theory* (2013), Chapters 1.1 and 2.

Optional further reading:

- Recht *Lecture* 1. In CS294 The Mathematics of Data Science lecture notes, UC Berkeley (2013).
- Kim, Pasupathy, Henderson *A Guide to Sample-Average Approximation*. In: Handbook of simulation optimization (2015).

Let's wrap up here



Figure 3: There's *always* a relevant XKCD

Thank you, and see you next week!